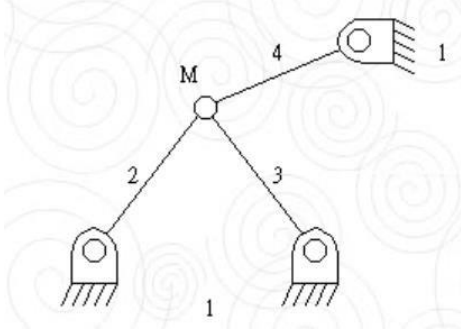


Final Examination (Dynamics of Machine Systems)

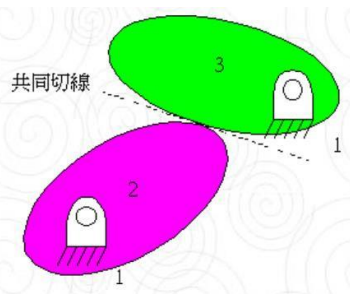
Upload deadline: 2021/6/23 24:00

1. Calculate the Mobility (DOF) of the 2-D or 3-D mechanical system (10%)

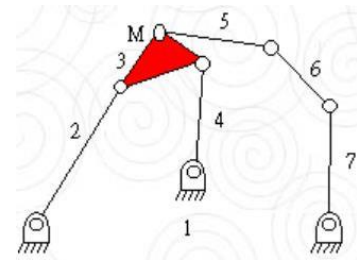
(a)



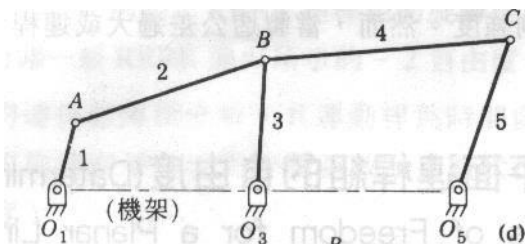
(b)



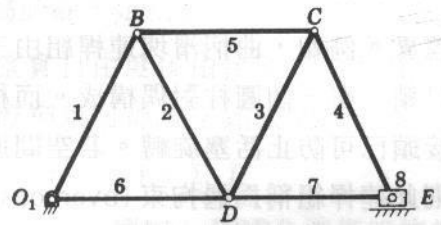
(c)



(d)



(e)



2. In the offset slider crank mechanism shown in Fig. 1 below the constrained path of the pin on the slider does not extend through the center of rotation of the crank. Given the lengths L_1 , L_2 and L_3 and the crank angle θ_2 , the position of the slider L_4 and the interior joint angles θ_3 and γ could be determined by the equations of $f(L_1, L_2, L_3, \theta_2)$. Please derive these equations. (10%)

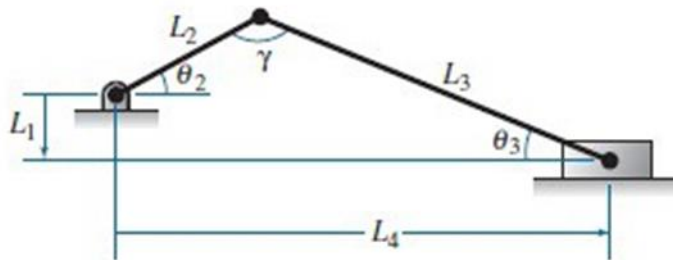


Fig. 1

3. As shown in Fig. 2, the pendulum(AB) has the initial angle 30° with respect to horizontal positive x-axis. If the pendulum has mass $m=2\text{kg}$, length $l=0.45\text{m}$, gravity $g=9.8\text{m/s}^2$ and release from an initial angular velocity 3 rad/s (CCW). Please solve for the angular acceleration and reaction force of revolute joint A at the release instant. (10%)

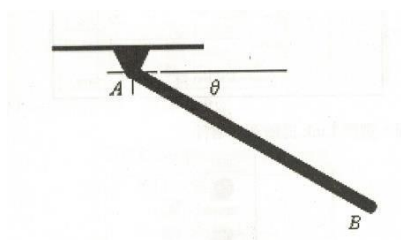


Fig. 2

4. The 4-Bar-Linkage as shown in Fig. 3, Link#2 rotates with constant angular velocity $\omega_2 = 1 \text{ rad/s}$ (CCW). If $O_2O_4=20\text{mm}$, $O_2A=20\text{mm}$, $O_4B=40\text{mm}$. Link#2(O_2A) and Link#4(O_4B) are perpendicular to the horizontal axis. Please use complex analysis method to solve for Link#3(AB) and Link#4(O_4B) angular velocities ω_3 and ω_4 , also the angular accelerations α_3 and α_4 . (10%)

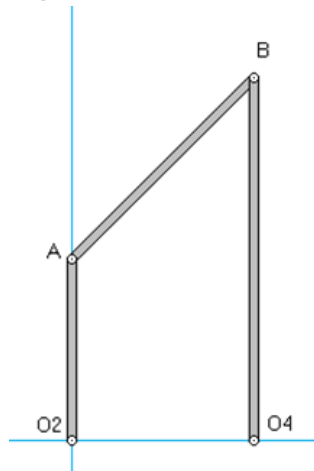


Fig. 3

5. As shown in Fig. 4, a single degree of freedom mass-spring system consists of a $m=5\text{kg}$ mass suspended by a linear spring which has a stiffness coefficient of $k=500\text{N/m}$. The mass is given an initial displacement of 0.5m and released from the initial velocity condition $v_0=10\text{m/s}$. Determine the system (a) Differential equation of motion, (b) Circular Natural Frequency, Natural Frequency and Period, (c) Dynamic response. (10%)

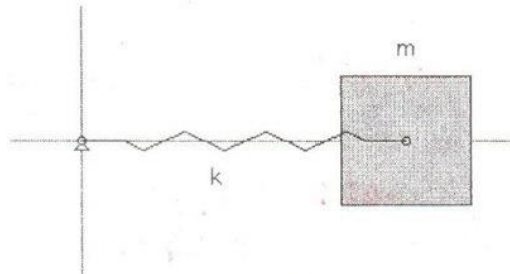


Fig. 4

6. As shown in Fig. 5, a single degree of freedom mass-spring system consists of a $m=10\text{kg}$ mass suspended by a linear spring which has a stiffness coefficient of $k=250\text{N/m}$. The system is subjected to a harmonic forcing function which has the amplitude 10N and frequency 5rad/s ($F(t)=10\sin(5*t)$). The mass is given an initial displacement of 1m and released from the rest condition. Determine the system (a) Differential equation of motion, (b) Circular Natural Frequency and Period, (c) Dynamic response. (10%)

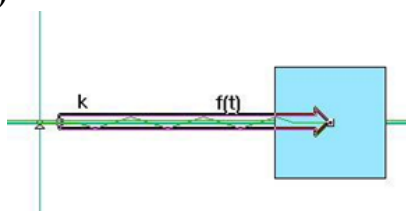


Fig. 5

7. A 3mm module, 20° pinion of 18 teeth drives a gear of 45 teeth. The pinion rotates with an angular velocity 9 rad/s (CCW). Calculate (A) Radius of pitch circle (B) Radius of base circle (C) Dedendum (D) Addendum (E) Diametral pitch (F) Center distance (G) The angular velocity of gear (magnitude and direction) (H) Contact Ratio. (10%)
8. A 0.3-module pinion of 34 teeth drives a gear with 60 teeth. If the center distance is increased by 0.127 mm, compare the backlash produced with pressure angles of 14.5° , 20° , and 25° . (10%)
9. A three-threaded worm drives a 35-tooth worm gear having a pitch diameter of 207.8 mm and a helix angle of 21.08° . If the shafts are at right angles, calculate the lead and the pitch diameter of the worm. (10%)
10. A planetary gear train for a two-speed aircraft supercharger drive is shown in Fig. 6. Gear 2 is driven by a 63-tooth gear (not shown) which operates at 2400 rpm. At high speed, gear 2 connects to the supercharger shaft through additional gearing. At low speed, gear 7 is held stationary and shaft B is connected to supercharger shaft with the same gear ratio as was used between gear 2 and the supercharger shaft. If the supercharger operates 24000 rpm at high speed, calculate the low speed value. (10%)

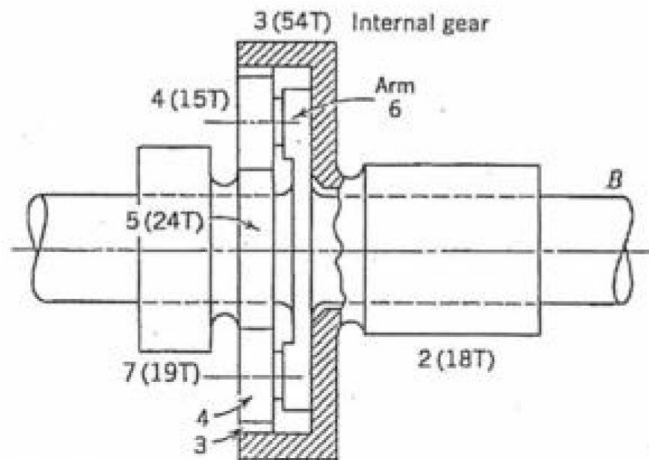


Fig. 6

11. In the planetary reduction unit shown in Fig. 7, gear 2 turns at 300 rpm in the direction indicated. Determine the speed and direction of rotation of gear 5. (10%)

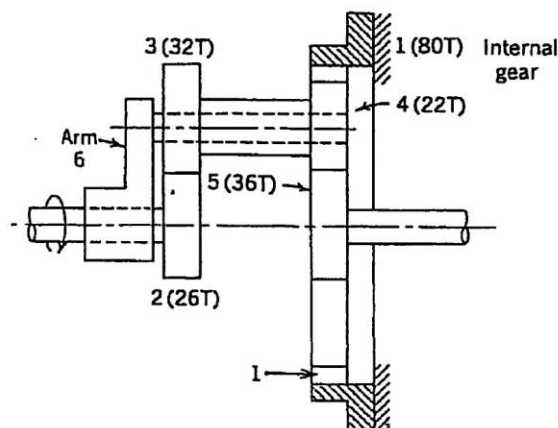


Fig. 7

- 1. Please submit the solution of final examination as soon as possible.**
- 2. Please upload your document file(*.docx) and insert hand-writing file (please scan to the image file save as JPG file) to the following website.**

Host Name: 140.130.17.62

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Please go to directory \Final-Examination, you can use your student ID to create a subdirectory. Finally, you should upload your files to your student ID subdirectory.